

# *Ultrasound beamforming*

*Massimo Mischi*

*Eindhoven University of Technology*

*m.mischi@tue.nl*



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## Reference:

Comprehensive Biomedical Physics, vol. 2,  
Chapter 2.13: J.M. Thijssen & M. Mischi,  
“Ultrasound Imaging Arrays” Elsevier, 2014.

# Frequency analysis

Fourier transformation

$$F(\omega) = \int_{-\infty}^{\infty} f(t)e^{-j\omega t} dt$$

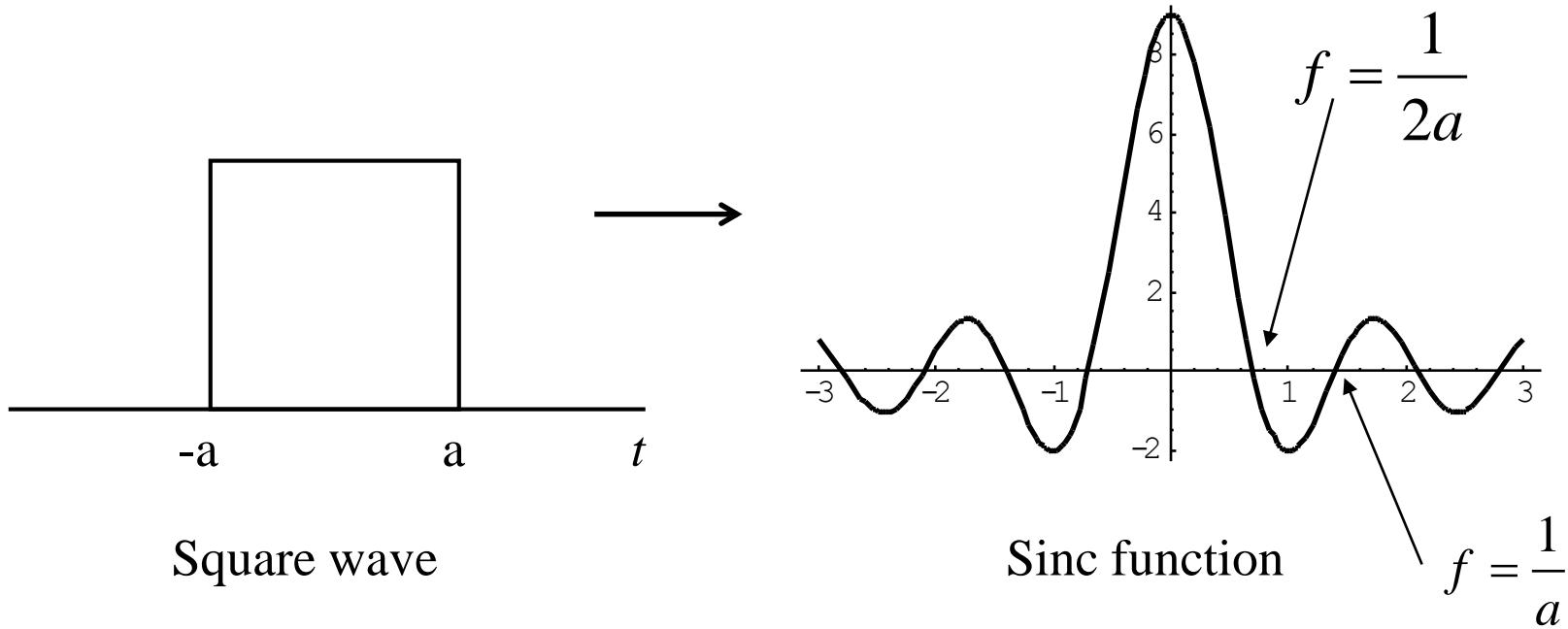
Fourier anti-transformation

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega)e^{j\omega t} d\omega$$

# Frequency analysis

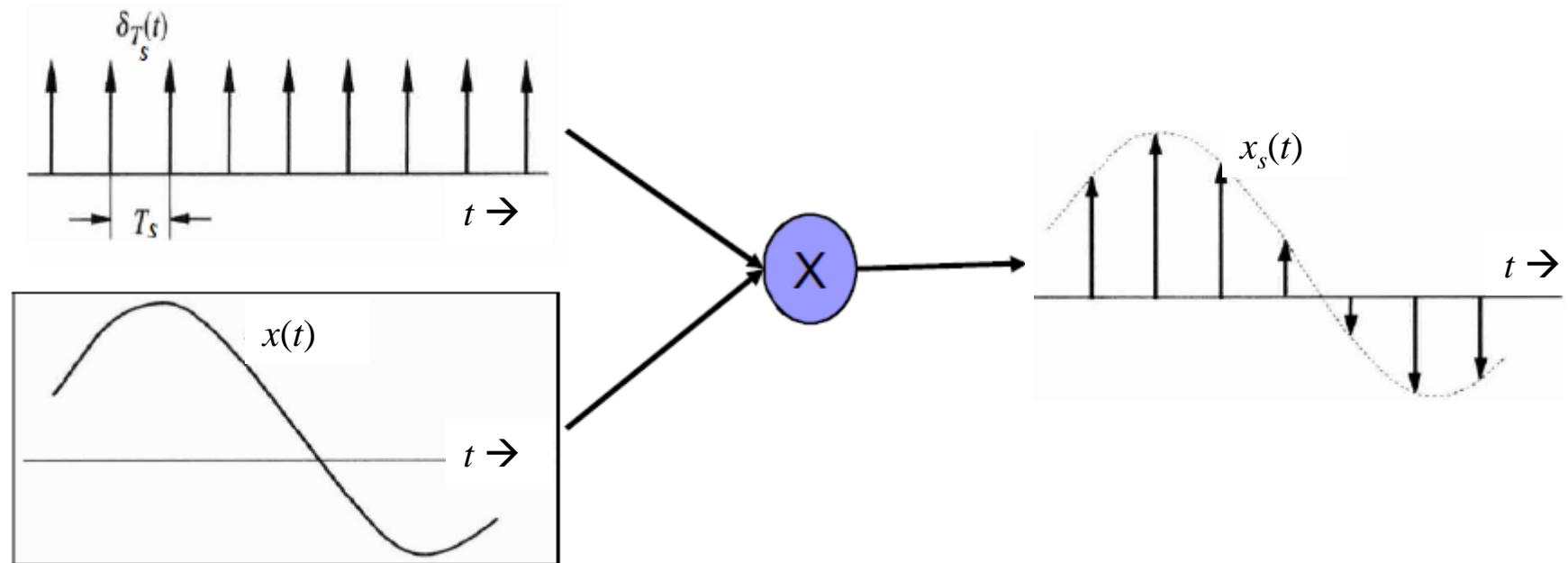
The Fourier transform permits the evaluation of the behavior of a system for different frequencies  $f = \omega/2\pi$ .

$$\Pi_a(t) \xrightarrow{F} 2a \cdot \text{sinc}(2\pi af)$$



# Sampling theorem

Sampling  $x(t)$  is equivalent to multiply it by a train of impulses...



# In formulas...

Time domain

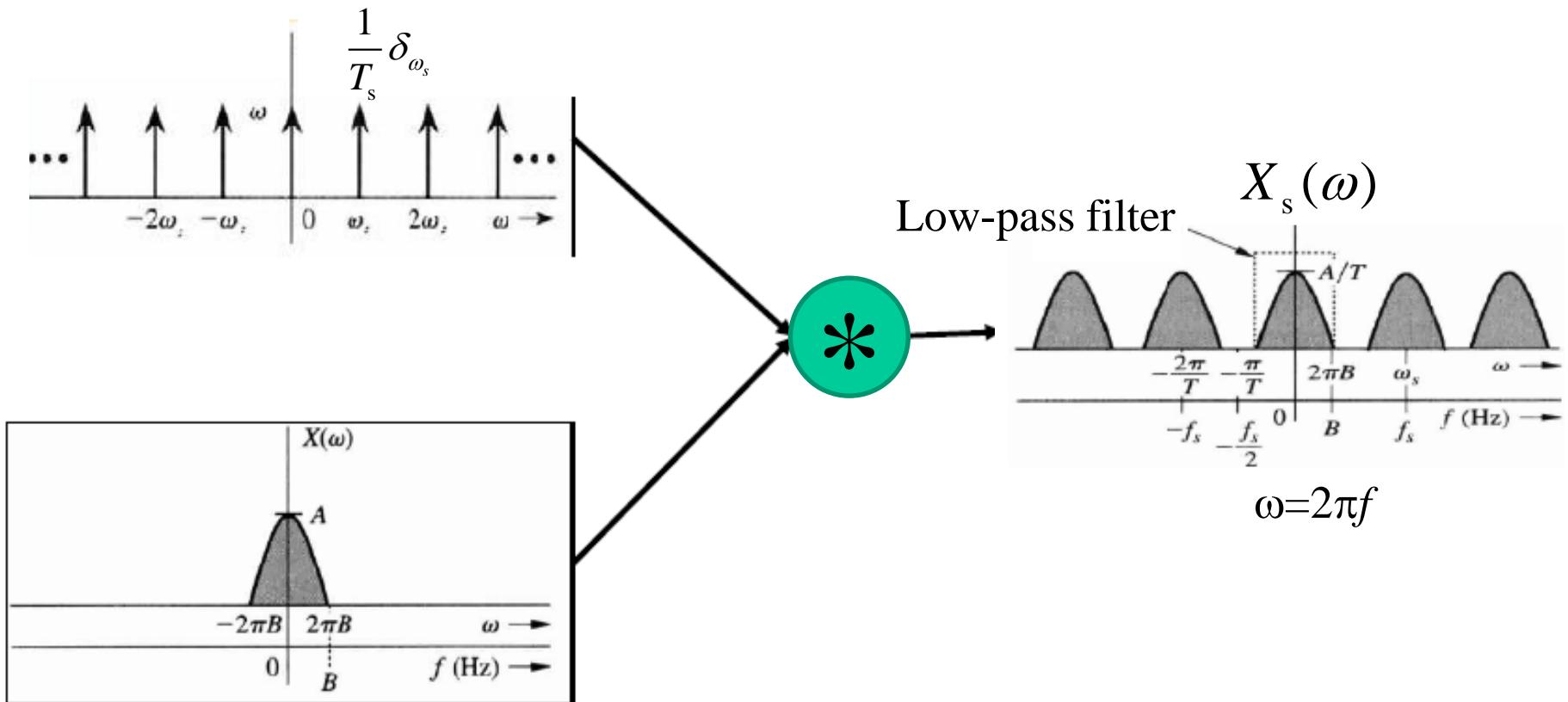
$$x_s(t) = x(t)s(t) = x(t) \sum_{n=-\infty}^{\infty} \delta(t - nT_s)$$

Frequency domain

$$X_s(\omega) = X(\omega) * \frac{1}{T_s} \sum_{n=-\infty}^{\infty} \delta(\omega - n\omega_s) = \frac{1}{T_s} \sum_{n=-\infty}^{\infty} X(\omega - n\omega_s)$$

Result obtained by using the Fourier expansion of a periodic function (train of pulses).

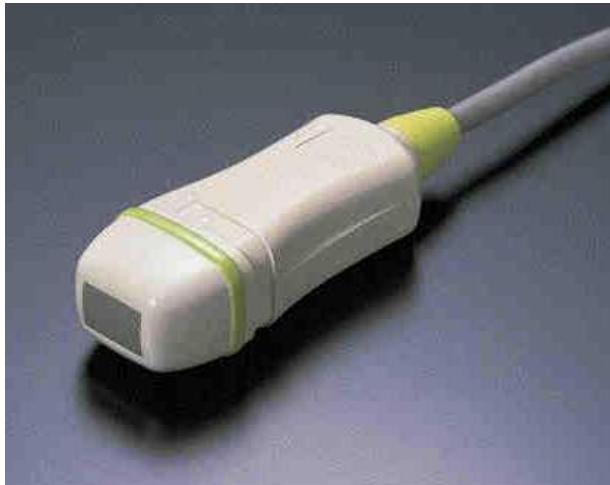
# Graphically...



In order to avoid aliasing, the **Nyquist** condition must be fulfilled:  $f_s > 2B$

# Array transducers

sector



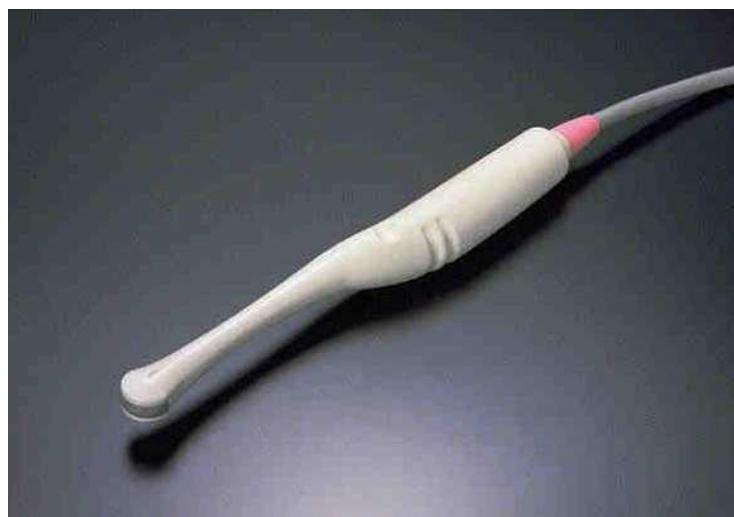
convex



linear



transvaginal/transrectal



transesophageal



# Wave equation

$$\frac{\partial^2 A}{\partial z^2} = \frac{1}{c^2} \frac{\partial^2 A}{\partial t^2}$$

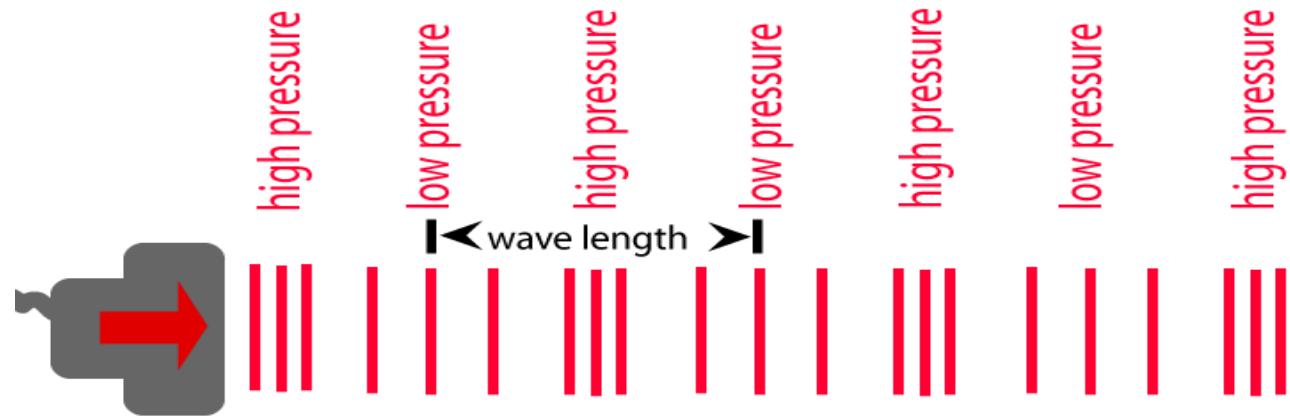
$$A(t, z) = A_0 e^{ik(ct-z)} \rightarrow \text{Re}[A(t, z)] = A_0 \cos(k(z - ct))$$

$A$  = particle displacement

$c$  = wave propagation velocity

$$k = \text{wave number} = 2\pi f v^{-1} = 2\pi \lambda^{-1}$$

↑                      ↑  
 Wave                  Wave  
 frequency          length



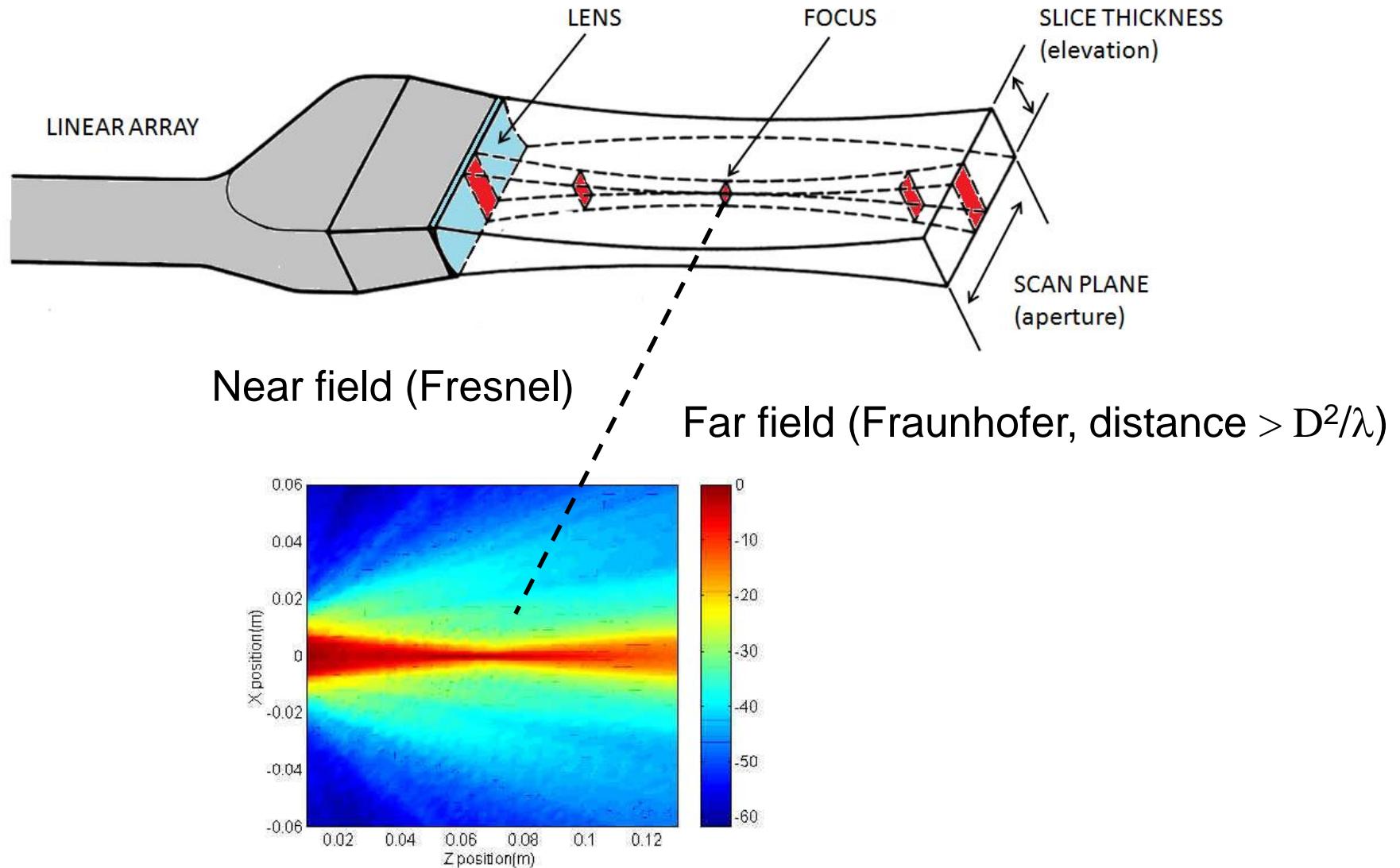
Relation pressure-displacement

$$p = \rho c \frac{\partial A}{\partial t}$$

$p$  = pressure [Pa]

$\rho$  = medium density [ $\text{kg m}^{-3}$ ]

# Pressure field

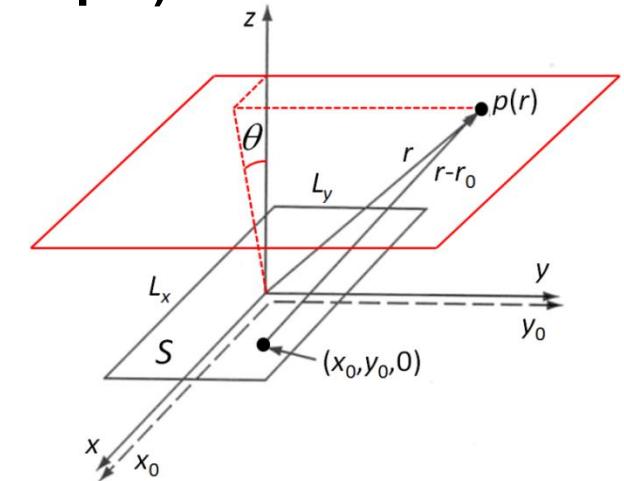


# Generated pressure field

## Rayleigh-Sommerfeld integral (based on Huygen's principle)

$$p(r, t) = \frac{j\rho c k}{2\pi} \iint_S \frac{e^{j[\omega t - k|r - r_0|]} v(r_0)}{|r - r_0|} dS = \frac{j\rho c k v_0}{2\pi} \iint_S \frac{e^{j[\omega t - k|r - r_0|]} a(r_0)}{|r - r_0|} dS$$

with  $v(r_0)$  the velocity on the emitting surface,  $S$ ,  
and  $a(r_0)$  a weighting function (apodization).

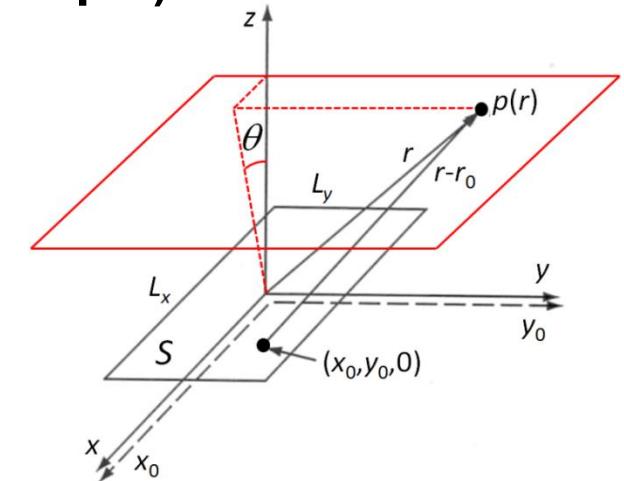


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with  $v(r_0)$  the velocity on the emitting surface,  $S$ ,  
and  $a(r_0)$  a weighting function (apodization).



## Fresnel approximation ( $r \gg r_0$ )

$$|r-r_0| = \sqrt{z^2 + (x-x_0)^2 + (y-y_0)^2} = z \sqrt{1 + \left(\frac{x-x_0}{z}\right)^2 + \left(\frac{y-y_0}{z}\right)^2} \cong z \left[ 1 + \frac{1}{2} \left( \frac{x-x_0}{z} \right)^2 + \frac{1}{2} \left( \frac{y-y_0}{z} \right)^2 \right] \cong z$$

$$p(r,t) = \frac{j\rho c k v_0}{2\pi z \lambda} e^{j(\omega t - kz)} e^{-jk\left(\frac{x^2+y^2}{2z}\right)} \iint_S a(x_0, y_0, 0) e^{-jk\left(\frac{x_0^2+y_0^2}{2z}\right)} e^{jk\left(\frac{xx_0+yy_0}{z}\right)} dx_0 dy_0$$

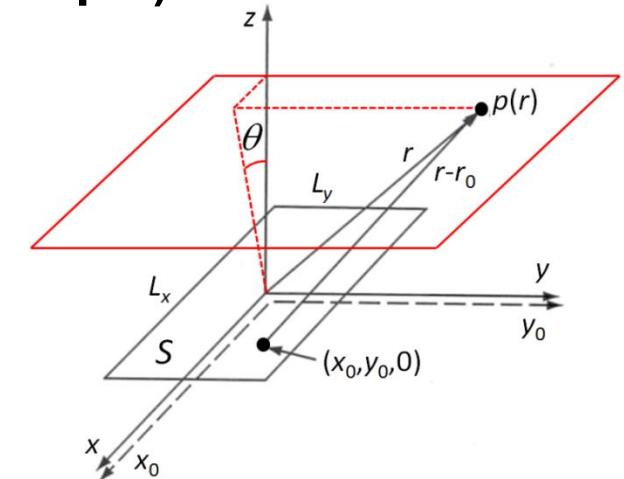
Maclaurin expansion  
 $\sqrt{1+a}, a \rightarrow 0$

# Generated pressure field

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Maclaurin expansion  
 $\sqrt{1+a}, a \rightarrow 0$

## Rectangular aperture

$$a(x_0, y_0, 0) = \prod_{L_x}(x_0) \cdot \prod_{L_y}(y_0), \text{ with } \prod_L(.) \text{ rectangular function of length } L.$$

# Generated pressure field

Separable integral:  $P(x, y, z) = P(x, z)P(y, z)$ .

Neglecting the phase  $j$  and oscillating exponent and considering a single integral:

$$p_x(x, z) = \psi_{0x} e^{-jk\left(\frac{x^2}{2z}\right)} \int_{-\infty}^{\infty} e^{-jk\left(\frac{x_0^2}{2z}\right)} \prod_{L_x} (x_0) e^{jk\left(\frac{xx_0}{z}\right)} dx_0,$$

$$\text{with } \psi_{0x} = \sqrt{\frac{\rho c k v_0}{2\pi z}}$$

# Generated pressure field

Separable integral:  $P(x, y, z) = P(x, z)P(y, z)$ .

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$$\text{with } \psi_{0x} = \sqrt{\frac{\rho c k v_0}{2\pi z}}$$

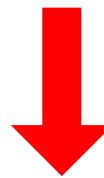
For  $\lambda z \gg x^2$  and  $\lambda z \gg x_0^2$ , i.e., far from the transducer surface (Fraunhofer approx), the quadratic phase terms can be neglected:

$$p_x(x, z) = \psi_{0x} \int_{-\infty}^{\infty} \left[ \prod_{L_x} [x_0] \right] e^{j2\pi\left(\frac{x}{\lambda z}\right)x_0} dx_0$$

## Fourier (anti)transform in space

$$p_x(x, z) = \psi_{0x} \int_{-\infty}^{\infty} \left[ \prod_{L_x} [x_0] \right] e^{j2\pi \left( \frac{x}{\lambda z} \right) x_0} dx_0 = L_x \psi_{0x} \text{sinc} \left( \frac{\pi x L_x}{\lambda z} \right)$$

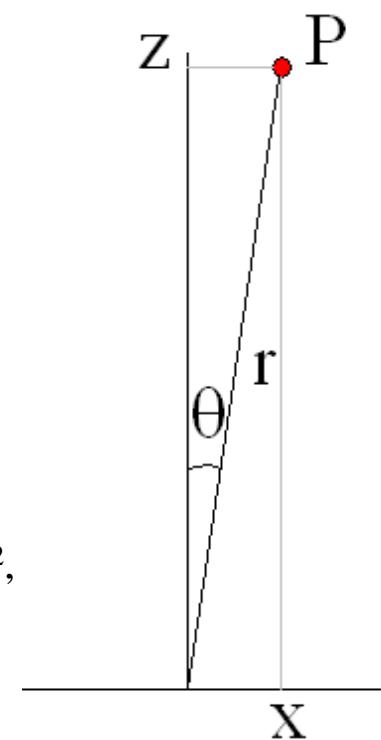
antittransform variable



$$p_x(x, z) \cong L_x \psi_{0x} \text{sinc} \left( \frac{\pi L_x}{\lambda} u \right)$$

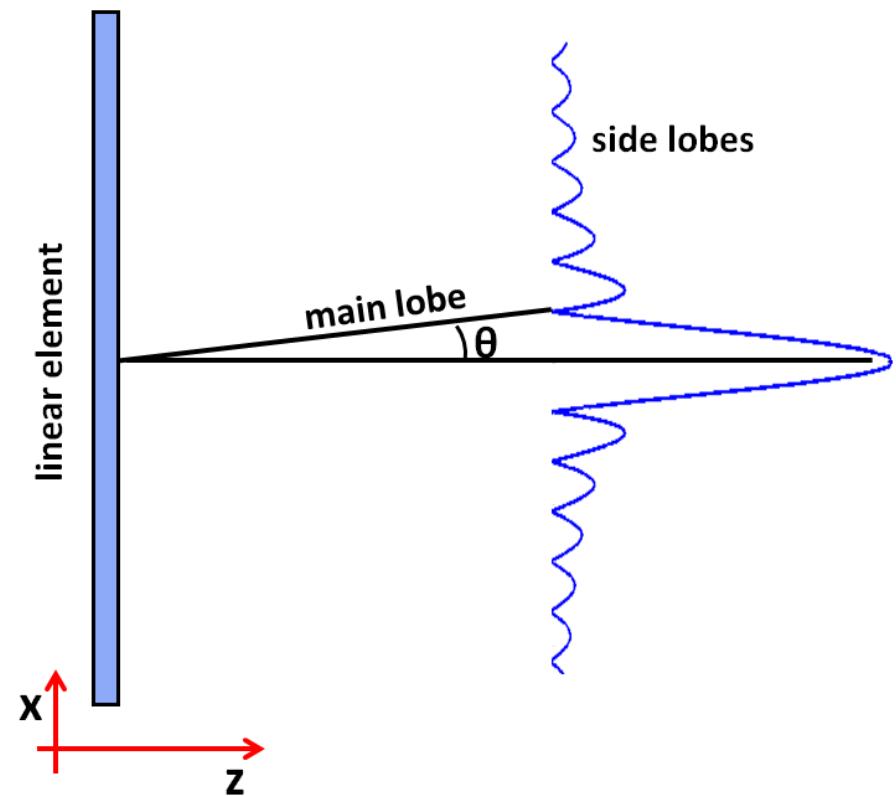
Based on **Fraunhofer** approximation  $\lambda z \gg x^2$ ,

$$x = |r| \sin \theta \cong z \sin \theta \equiv zu$$



$$p_x(x, z) \cong L_x \psi_{0x} \operatorname{sinc}\left(\frac{\pi L_x}{\lambda} \sin(\theta)\right)$$

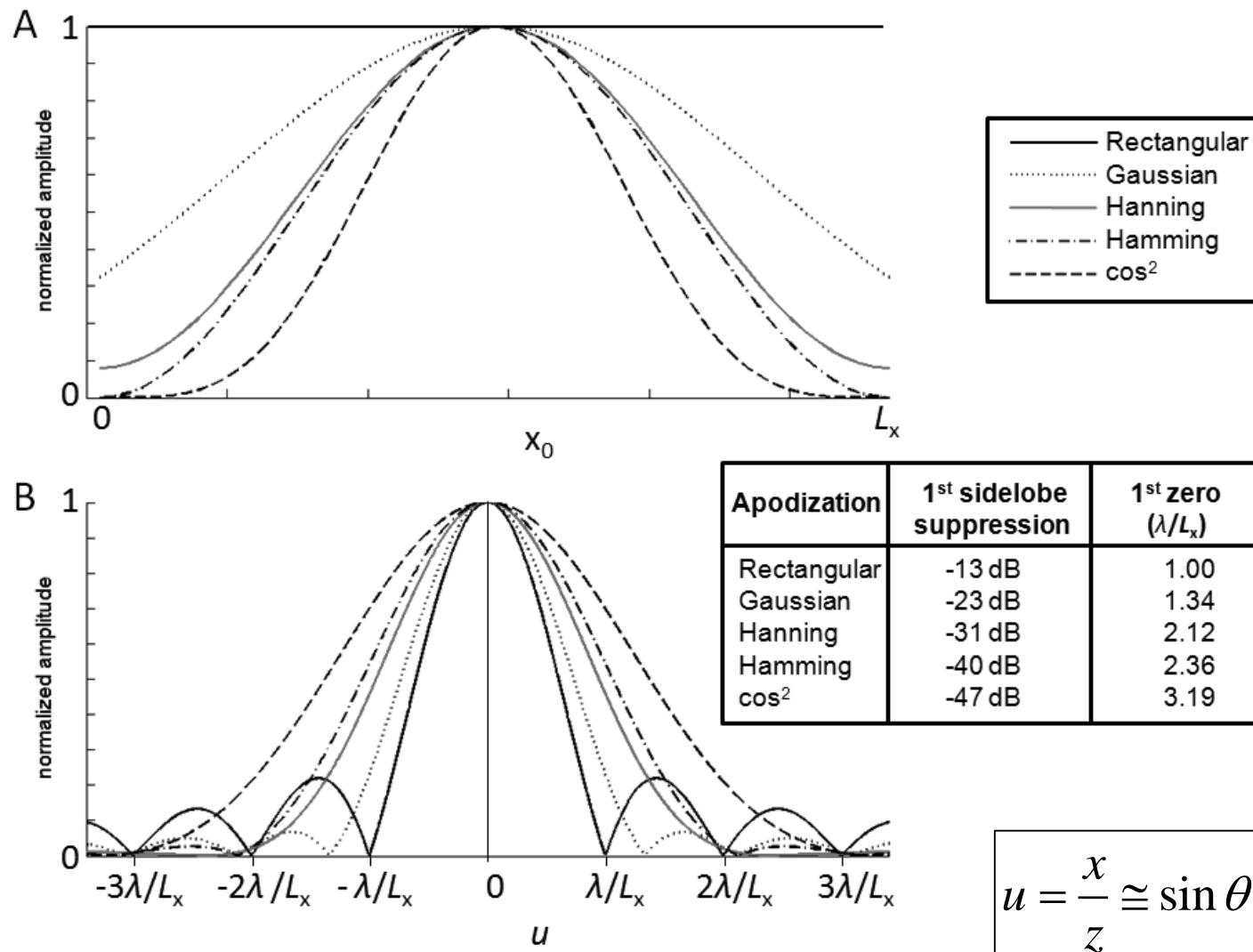
For  $\sin(\theta) = \frac{\lambda}{L_x} \rightarrow p_x(x, z) = 0$



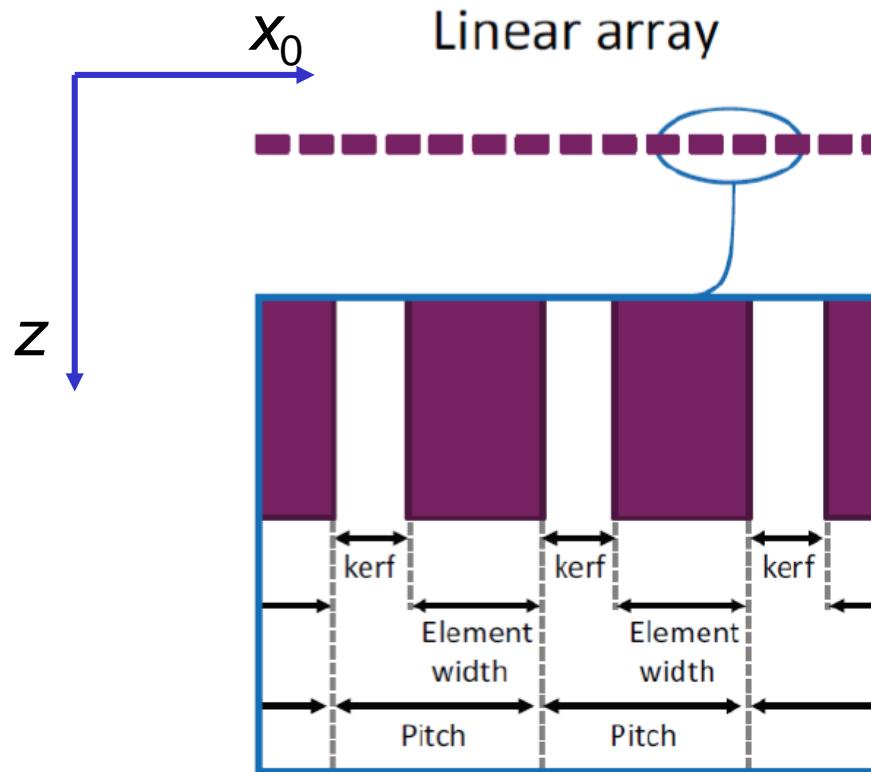
**Like in signal processing, windowing reduces the side lobes.**  
**Transducer windowing: “*Apodization*”.**

$$p_x(x, z) = \psi_{0x} \int_{-\infty}^{\infty} \left[ \prod_{L_x} [x_0] a(x_0) \right] e^{j2\pi \left( \frac{x}{\lambda z} \right) x_0} dx_0 = L_x \psi_{0x} A \left( \frac{x}{\lambda z} \right) \cong L_x \psi_{0x} A \left( \frac{u}{\lambda} \right)$$

# Apodization



# Multiple elements



$$\prod_{L_x} [x_0] \Rightarrow \prod_{L_x} [x_0] \left( \prod_w [x_0] * \sum_m \delta(x_0 - md) \right)$$

↑ Dirac impulse

↓ Pitch length

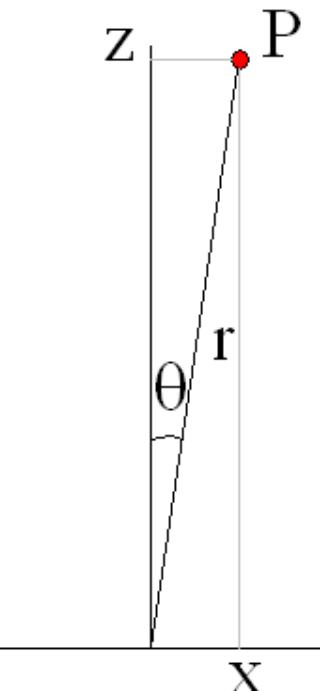
# Linear-array transducer

$$\begin{aligned}
 p_x(x, z) &= \psi_{0x} \mathfrak{I}^{-1} \left\{ \left( \prod_w [x_0] * \sum_m \delta(x_0 - md) \right) \prod_{L_x} [x_0] \right\} \\
 &= \psi_{0x} \mathfrak{I}^{-1} \left\{ \prod_w [x_0] \right\} \mathfrak{I}^{-1} \left\{ \prod_{L_x} [x_0] \sum_m \delta(x_0 - md) \right\}
 \end{aligned}$$



**Sampling theorem**

$$\begin{aligned}
 p_x(x, z) &= \psi_{0x} \frac{L_x w}{d} \operatorname{sinc} \left[ \frac{\pi w x}{\lambda z} \right] \sum_m \operatorname{sinc} \left[ \frac{\pi L_x}{\lambda} \left( \frac{x}{z} - \frac{m \lambda}{d} \right) \right] = \\
 &= \psi_{0x} \frac{L_x w}{d} \operatorname{sinc} \left[ \frac{\pi w x}{\lambda z} \right] \sum_m \operatorname{sinc} \left[ \frac{\pi L_x}{\lambda} \left( u - \frac{m \lambda}{d} \right) \right]
 \end{aligned}$$



$$x = |r| \sin \theta \approx z \sin \theta \equiv z u$$

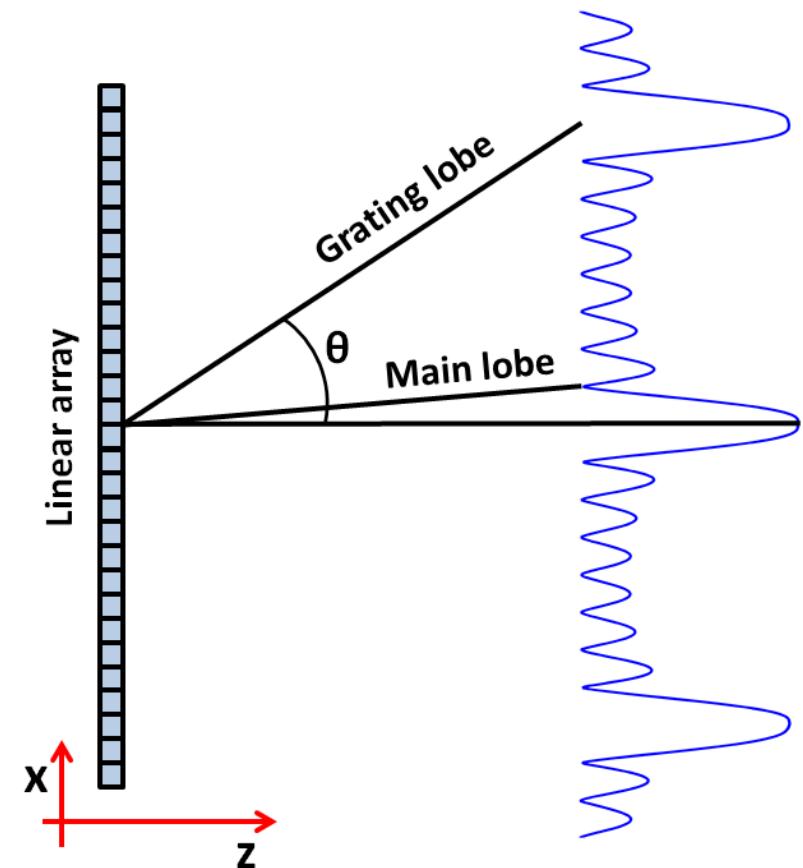
**Grating lobes are centered at angles such that the  $\operatorname{sinc}(.)$  argument equals zero.**

$$\theta_g = \pm \arcsin \left( \frac{m \lambda}{d} \right)$$

# Grating lobes

$$p_x(x, z) = \psi_{0x} \frac{L_x w}{d} \operatorname{sinc}\left[\frac{\pi w x}{\lambda z}\right] \sum_m \operatorname{sinc}\left[\frac{\pi L_x}{\lambda} \left(u - \frac{m\lambda}{d}\right)\right]$$

$$\theta_g = \pm \arcsin\left(\frac{m\lambda}{d}\right)$$



# Summary

Aperture  $L_x$

$$\prod_{L_x} [x_0]$$



$$\text{sinc}\left(\frac{\pi u L_x}{\lambda}\right)$$

Pulse train with period  $p$  (pitch)

$$\sum_m \delta(x_0 - md)$$



$$\sum_m \text{sinc}\left[\frac{\pi L_x}{\lambda}\left(u - \frac{m\lambda}{d}\right)\right]$$

Single element with size  $w$

$$\prod_w [x_0]$$



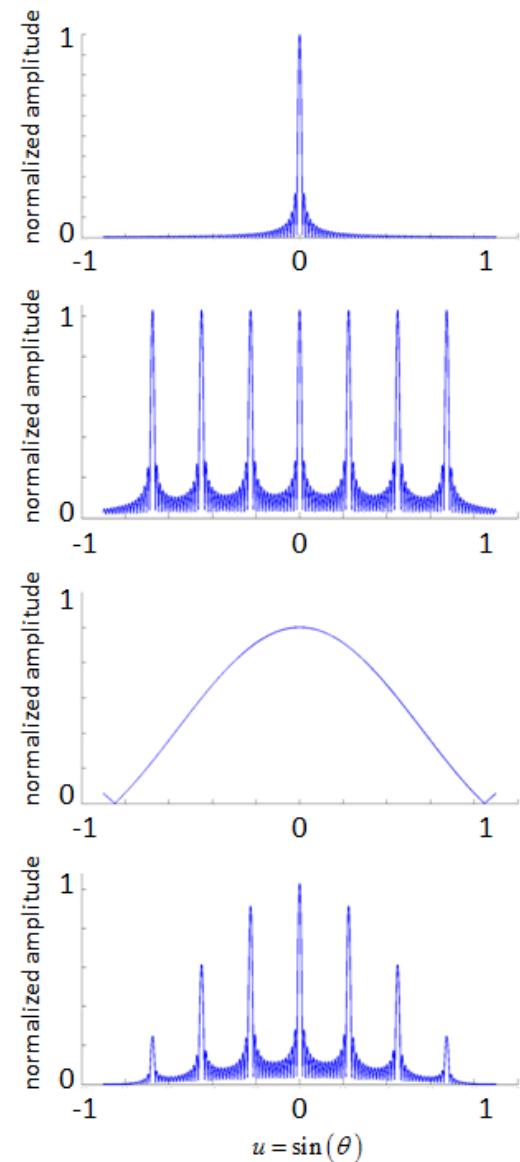
$$\text{sinc}\left[\frac{\pi w u}{\lambda}\right]$$

Full array with aperture  $L_x$

$$\prod_{L_x} [x_0] \cdot \left[ \prod_w [x_0] * \sum_m \delta(x_0 - md) \right]$$



$$\text{sinc}\left[\frac{\pi w u}{\lambda}\right] \sum_m \text{sinc}\left[\frac{\pi L_x}{\lambda}\left(u - \frac{m\lambda}{d}\right)\right]$$



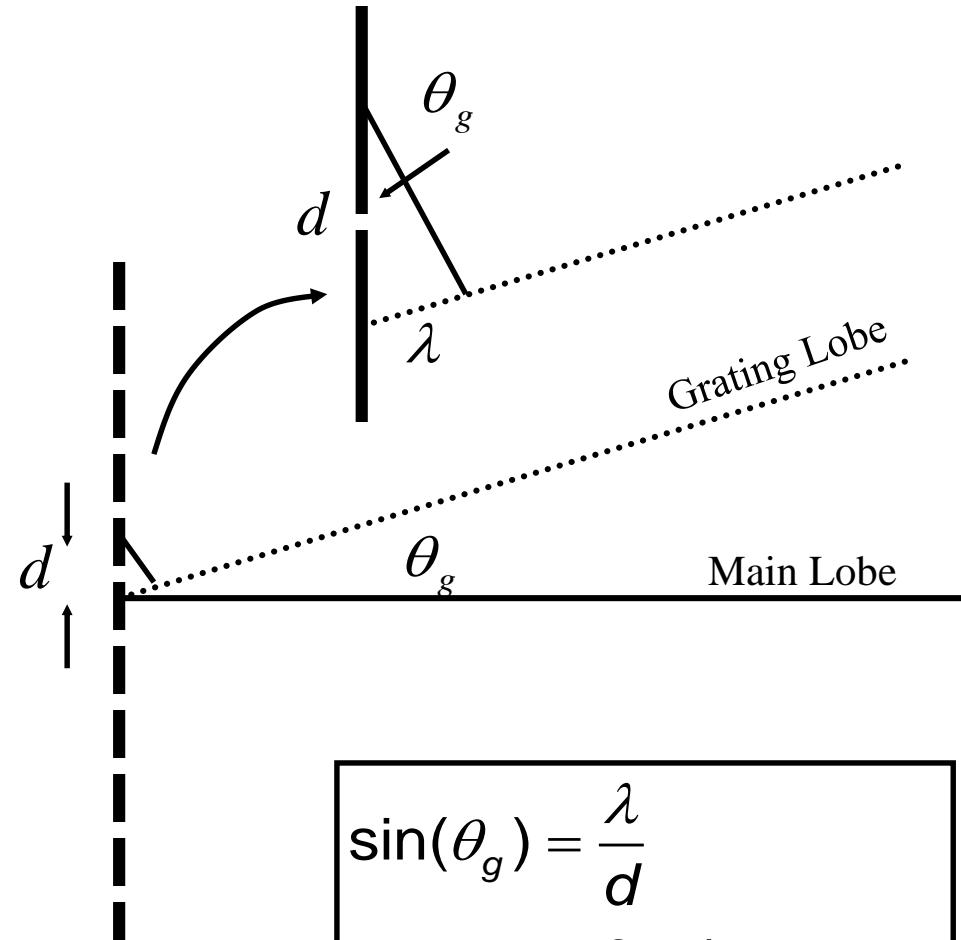
# Grating lobe example

How many elements?

What spacing?

Linear array:

- 32 element array
- 3 MHz
- ‘pitch’  $d = 0.4 \text{ mm}$
- $\lambda = 0.51 \text{ mm}$
- $L_x = N d = 13 \text{ mm}$



$$\sin(\theta_g) = \frac{\lambda}{d}$$

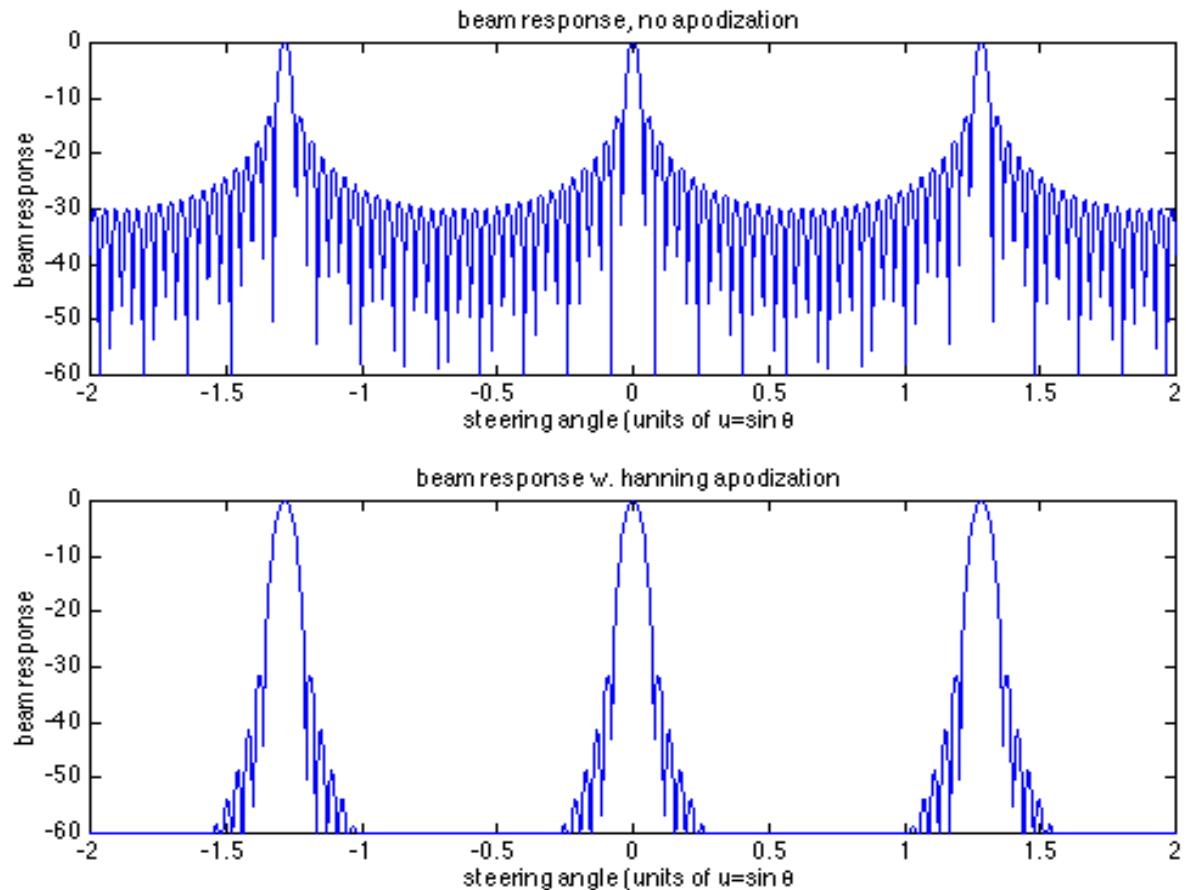
$$\sin(\theta_g) = \frac{0.51}{0.4} = 1.275$$

# Apodization example

Same array:

- 32 element array
- 3 MHz
- pitch  $d = 0.4$  mm
- $\lambda = 0.51$  mm
- $L_x = N d = 13$  mm.

- With & w/o Hanning windowing.
- Sidelobes way down.
- Mainlobe wider.
- No effect on grating lobes.



# Electronic beam steering

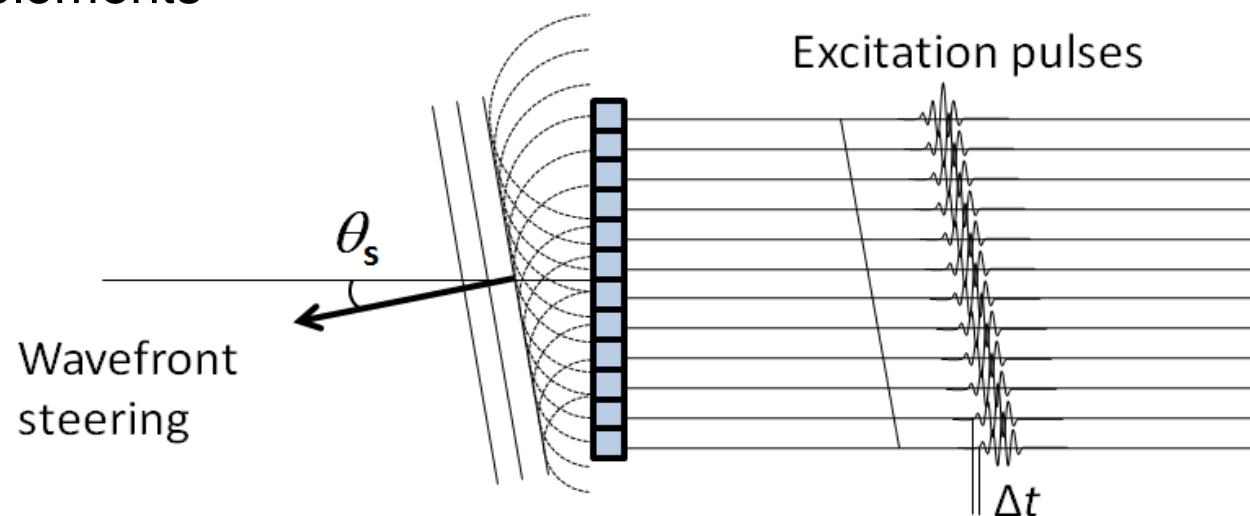
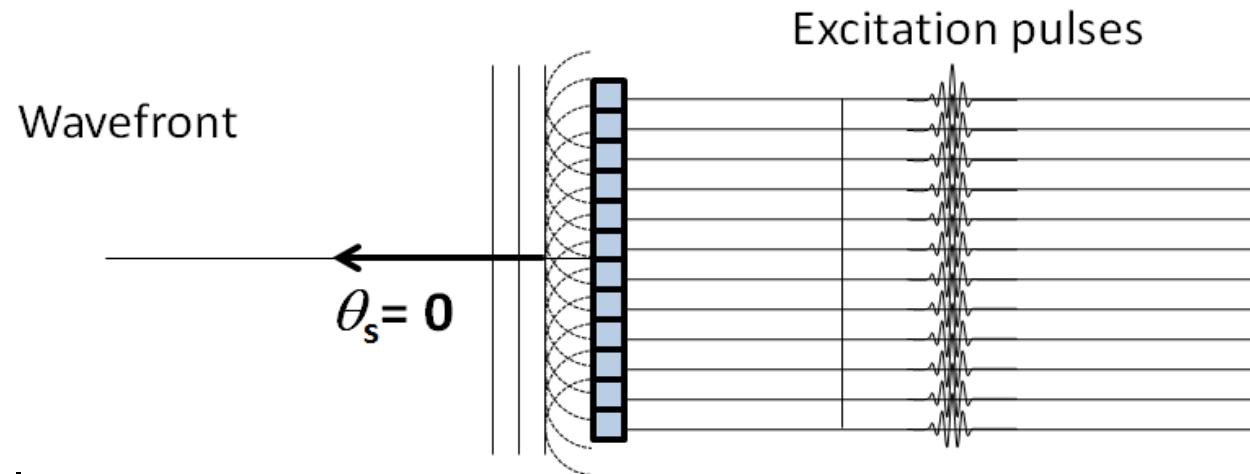
Beam steering by systematic excitation delays.

$$\theta_s = \sin^{-1} \left( \frac{c_0 \Delta t}{d} \right)$$

$d$  = pitch, distance between elements

$c_0$  = ultrasound velocity

$\Delta t$  = activation delay



# Electronic beam steering

Beam steering by systematic excitation delays.

$$\theta_s = \sin^{-1} \left( \frac{c_0 \Delta t}{d} \right)$$

$$u_s = \sin(\theta_s)$$

$$p_{xs}(u, u_s, \lambda) = \psi_{0x} \frac{L_x w}{d} \operatorname{sinc} \left[ \frac{\pi w x}{\lambda z} \right] \sum_m \operatorname{sinc} \left[ \frac{\pi L_x}{\lambda} \left( u - \frac{m \lambda}{d} - u_s \right) \right]$$

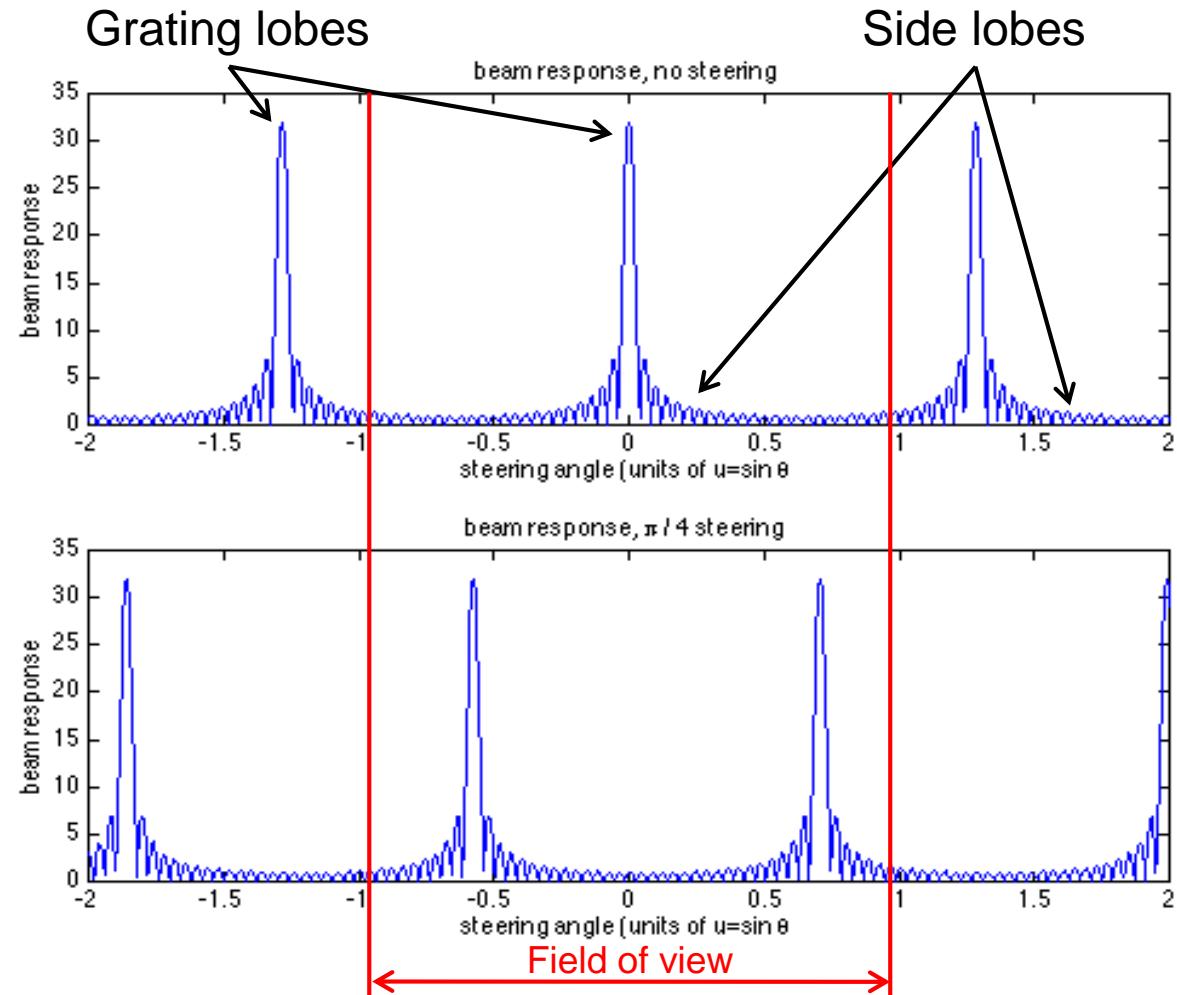
# Array design

How many elements?

What spacing?

Linear array:

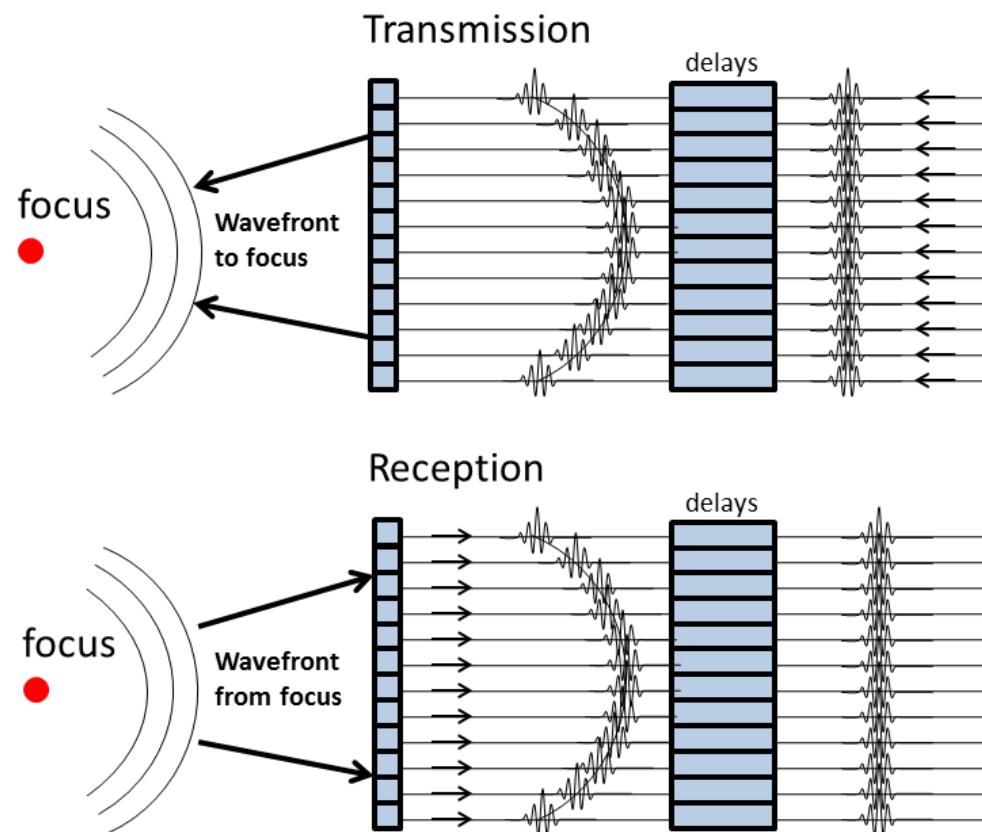
- 32 element array
- 3 MHz
- ‘pitch’  $d = 0.4$  mm
- $\lambda = 0.51$  mm
- $L_x = N d = 13$  mm
- $\theta_s = 45$  degrees ( $\pi/4$ )



$d \leq \frac{\lambda}{2}$  Even steering by 90 degrees ( $\sin \theta = 1$ ), the first grating lobes remain outside the field of view. Like Nyquist limit for array transducers!

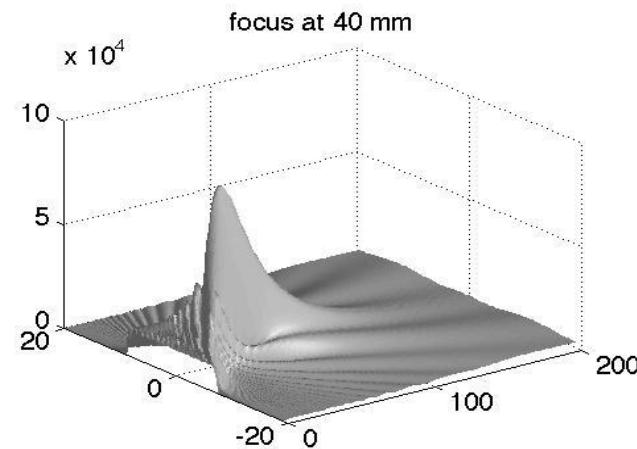
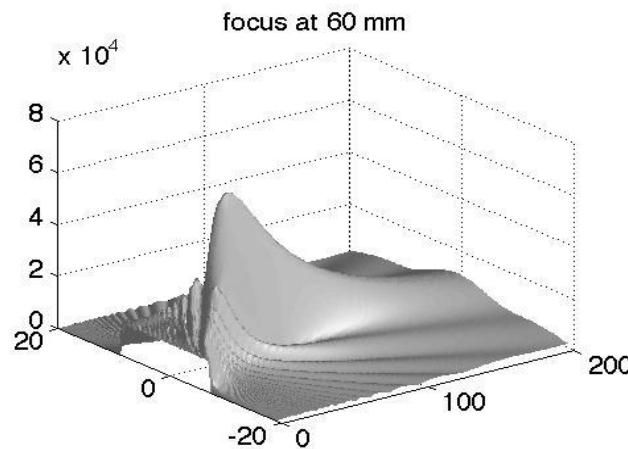
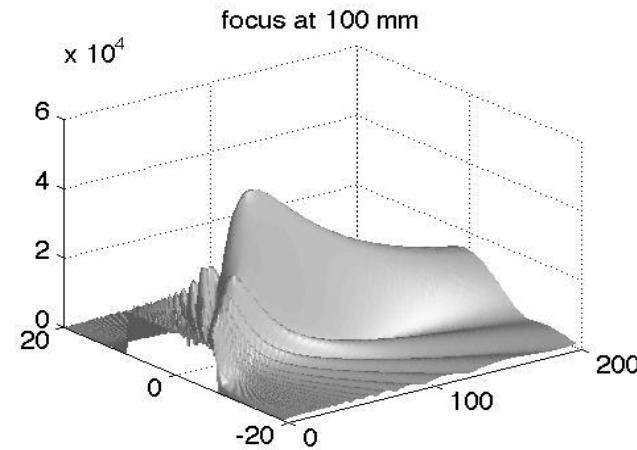
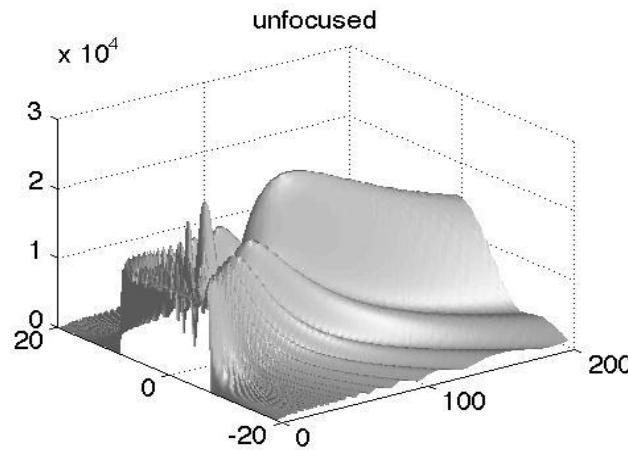
# Electronic focusing

## Beam forming for dynamic focusing



# Focusing effects on the ultrasound beam

## Electronic Focusing

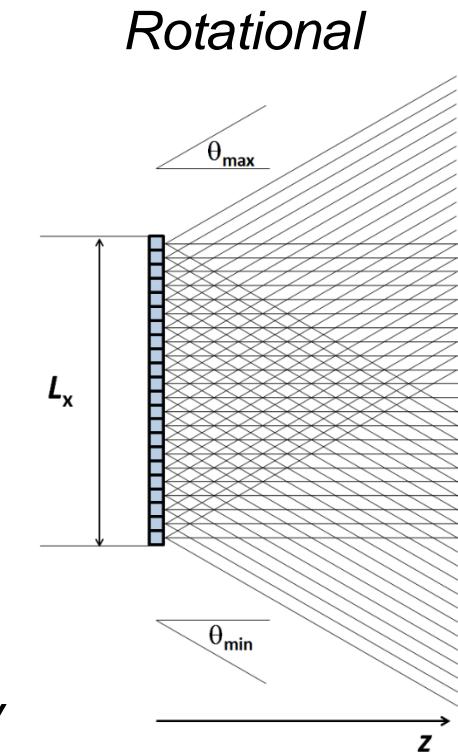
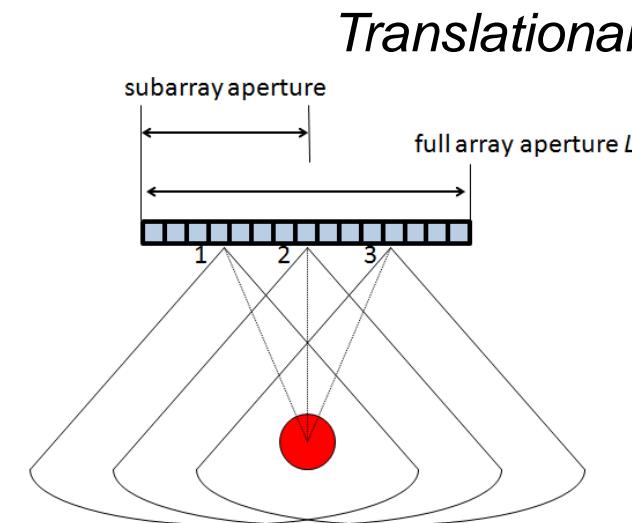


# Compounding

Improved SNR by averaging different images with same target but different speckle noise.

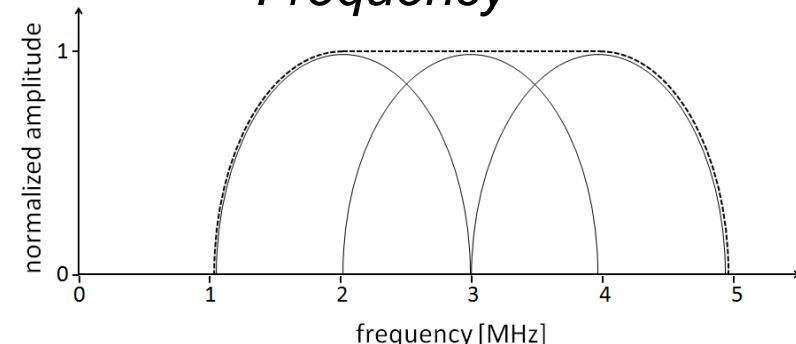
## Spatial compounding

- Translational  
(sub-aperture linear stepping)
- Rotational (steering)

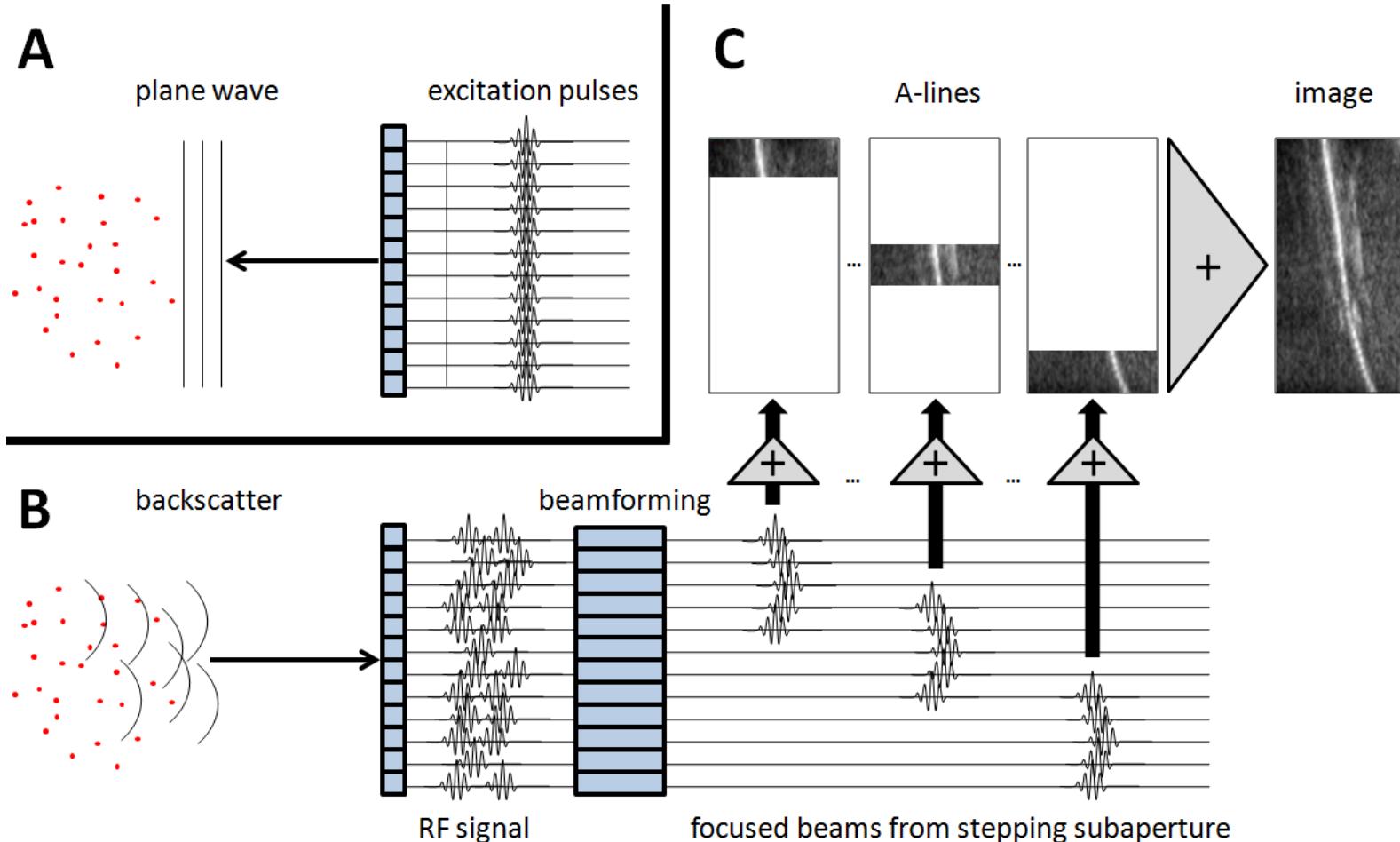


## Frequency compounding

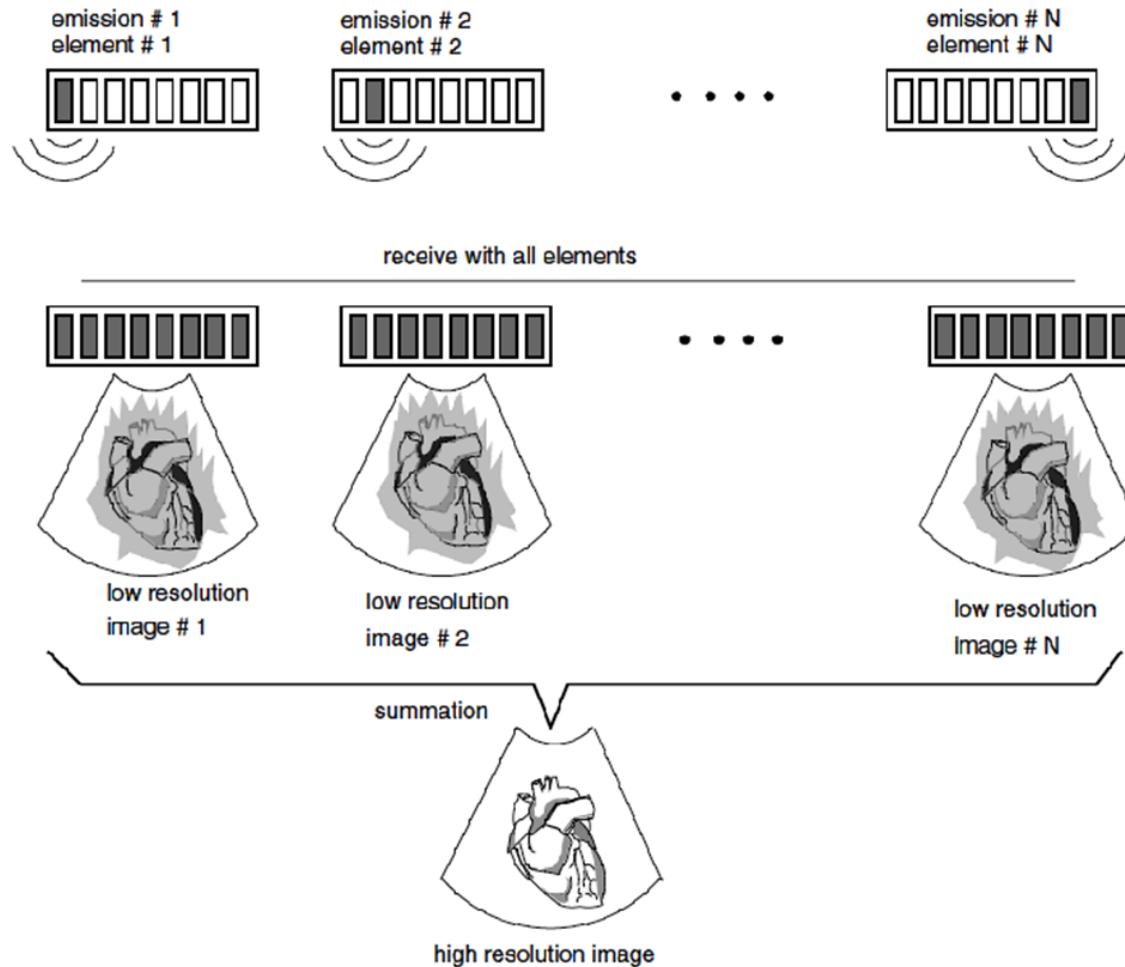
- Broadband transducer
- Long pulses (lower axial resolution)



# Plane wave imaging



# Synthetic aperture



Sequential firing by each element.

Reception by all elements generating low-resolution focused images.

Summation of low resolution images to form a high-resolution focused images.

# Synthetic aperture

Conventional

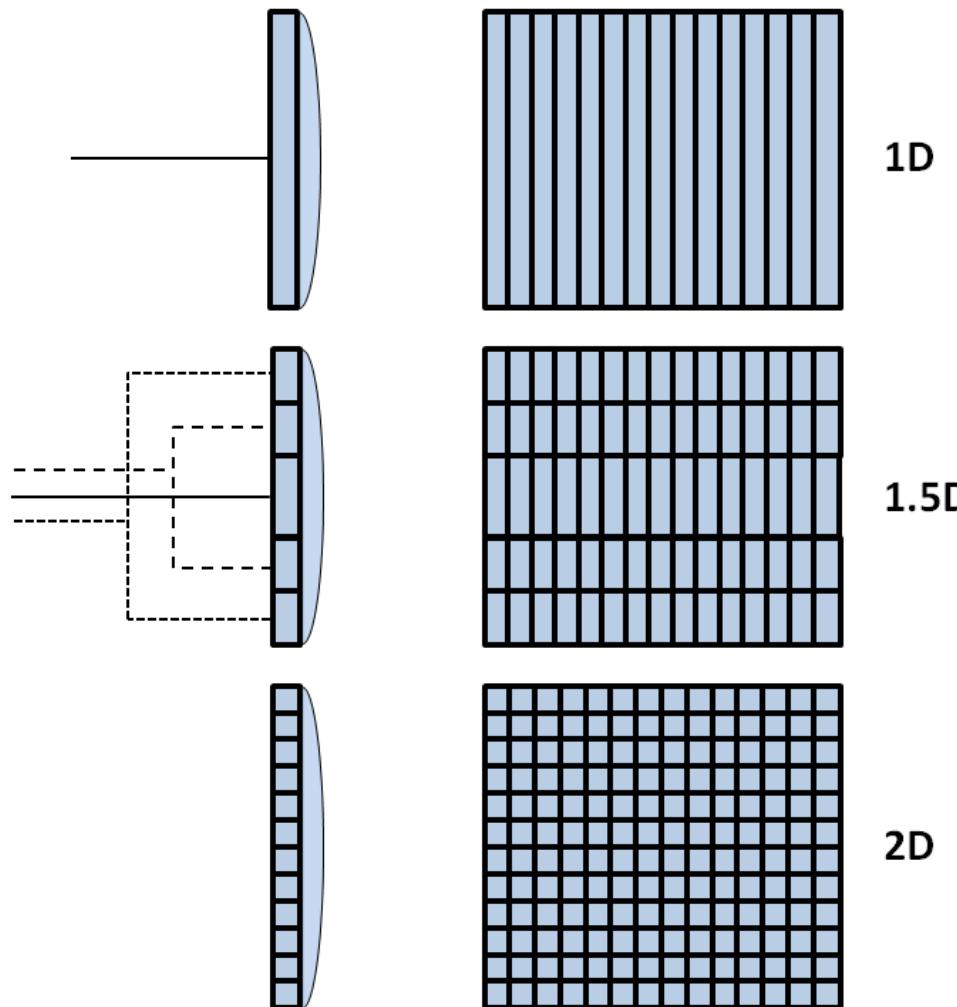


Synthetic aperture



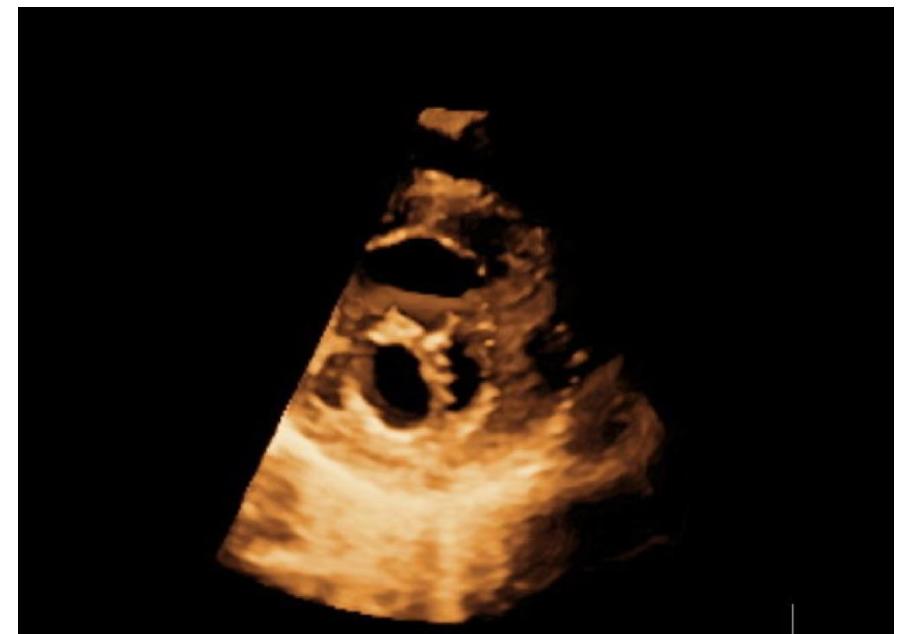
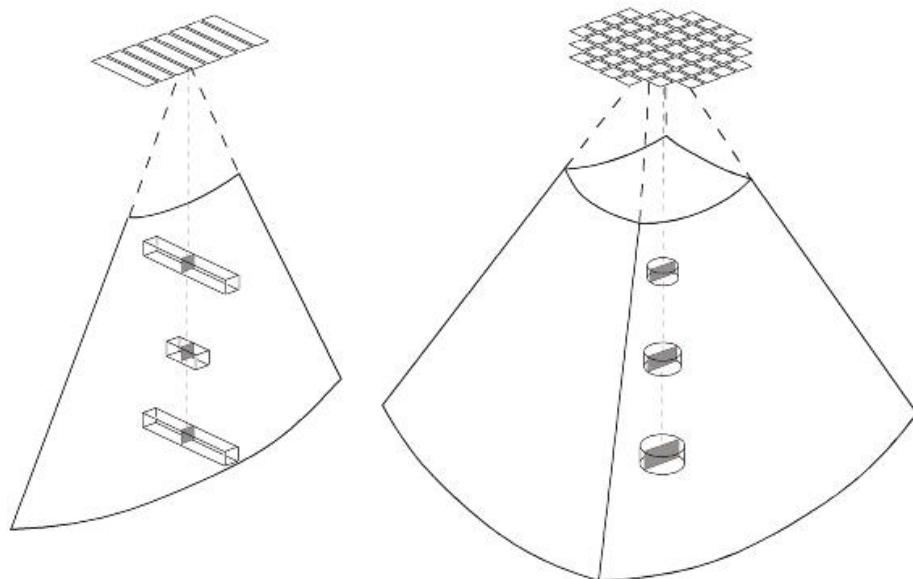
Jensen JA, Nikolov SI, Gammelmark KL, et al. (2006) Synthetic aperture ultrasound imaging. Ultrasonics 44: e5–e15.

# Array transducers' classification



# 3-D echography

1D array → 2D array  
2D imaging → 3D imaging



3-D echocardiographic view of  
a double-orifice mitral valve

# Thank you!



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